# 42STH38 NEMA-17 Bipolar Stepper with 99.51:1 Gearbox



This NEMA-17 motor has an integrated Planetary gearbox with a  $99^{1044}/_{2057}:1$  ratio.It comes with the rear shaft exposed, so you can mount an encoder or shaft coupler. See the "Compatible Products" tab for a complete list of attachments.

When connected to a 1067 — PhidgetStepper Bipolar HC, the 3329 has a maximum speed of 34 RPM. At the output of the gearbox, the step angle is approximately 0.018?°. When using the step angle in calculations, you should derive the exact step angle by dividing 1.8?° by the gearbox reduction ratio. See the "Compatible Products" tab for wiring details.

At 1.7 Amps, this gearbox stepper can produce a maximum torque of 250 kg-cm. However, the gearbox is only rated for 48 kg-cm of continuous torque, and 100 kg-cm for brief overloads. Loading this gearbox stepper beyond the torque rating of the gearbox will shorten its useful life.

#### Connection

This motor must be controlled by a constant current or chopper drive controller. You can find a list of suitable controllers on the **Compatible Products**tab. There you will also find compatible attachments such as encoders, mounting hardware, and transmission hardware.

## Warning

Connecting the motor directly to a power supply will destroy the motor and void the warranty. If you want to check your motor make sure it is connected to a constant current / chopper drive controller.

## **Product Specifications**

## **Motor Properties**

Motor Type Bipolar Stepper

Manufacturer Part Number 42STH38-1684B / 36JXS60K99.51

Step Angle 0.018?°
Step Accuracy ? $\pm$  5 %
Holding Torque 48 kg?·cm
Rated Torque 48 kg?·cm

Maximum Speed (w/1067 Motor Controller) 34 RPM

Acceleration at Max Speed (w/1067 Motor Controller)

1.2E+06 1/16 steps/sec?<sup>2</sup>

## **Electrical Properties**

Recommended Voltage 12 V DC Rated Current 1.7 A Coil Resistance 1.7 ?© Phase Inductance 3.2 H

## **Physical Properties**

Shaft Diameter 8 mm
Rear Shaft Diameter 3.9 mm
Mounting Plate Size NEMA — 17
Weight 564 g
Number of Leads 4
Wire Length 300 mm

# **Gearbox Properties**

Gearbox Type Planetary Gear Ratio 99  $^{1044}\square_{2057}$  : 1

Backlash Error  $1^{1}\square_{2}$ ?° Maximum Strength of Gears  $48 \text{ kg?} \cdot \text{cm}$  Shaft Maximum Axial Load 49.1 N Shaft Maximum Radial Load 98.1 N

### **Documents**

- Mechanical Drawings
- Stepper Motor and Controller Primer

# **Projects**

- Motor Music: Play MIDI Files using Phidget Stepper Motors (June 1, 2015)
- How To Avoid Resonance Issues in Stepper Motors (July 28, 2014)
- Steppers with Encoders: When Open-loop Control Is Not Enough (May 13, 2014)

#### **Motor Controllers**

This motor must be controlled by a stepper motor controller. This diagram shows how to connect the motor wires to the controller to produce a clockwise rotation in the stepper motor when increasing position. To wire for counter-clockwise rotation when increasing position, reverse the red and blue wires.

**Note:** Make sure to unplug the power cord from the motor controller before switching wires around.

The following stepper controllers can be used to drive this motor:

Product	Electrical Properties			
Part Number	Motor Position Resolution	Stepper Velocity Resolution	Stepper Velocity Max	Available Current per Coil Max
1067_0B	$^{1}\square_{16}$ Step (40-Bit Signed)	1 1/16 steps/sec	250000 1/16 steps/sec	4 A
STC1000_0	¹□ <sub>16</sub> Step (40-Bit Signed)	1 1/16 steps/sec	115000 1/16 steps/sec	4 A

#### **Encoders**

The rear shaft of this motor can be equipped with an encoder for applications

where you need to keep track of the exact position, velocity, or acceleration of the motor. The mounting holes on the back of this motor are compatible with the following encoders:

Product		Enc	perties	
Part Number	<b>Output</b>	Circuit Type	Encoder	Resolution Encoder Speed Max
3531_0	Push-Pull	(Single-Ended)	300 CPR	6000 RPM

# **Shaft Couplers**

If you need to connect the main shaft of this motor to the shaft of another device, you can use a shaft coupler:

Product			Physical Properties			
	Part Number	Inner Diameter	Material	Coupling Rated Torque	Cou	pling Rated Speed
	<u>3423_0</u>	8 mm	Aluminium 4.	1 kg?∙cm	10000	RPM
	<u>3427_0</u>	8 mm	Aluminium 60	.7 kg?∙cm	16000	RPM
	TRM4313 0	8 mm	Aluminum 35	.7 kg?·cm	12000	RPM