

# PhidgetAdvancedServo 1-Motor



**Note:** The 1066\_1B is identical to the 1066\_1, except that you have the option of whether you want to include the USB cable.

The PhidgetAdvancedServo 1-Motor allows you to control the position, velocity, and acceleration of one RC servo motor. The 1066 is powered solely by the USB cable — no additional power source is required.

The 1066 measures the power consumption of the servo, and powers servo motors of up to 450mA.

The AdvancedServo connects directly to a computer's USB port.

## **Comes packaged with**

- A hardware mounting kit (4 nuts and bolts (M3), 4 plastic spacers)

## **Product Specifications**

### **Servo Controller**

API Object Name	AdvancedServo
Number of Motor Ports	1
Pulse Width Min	83.3 ns
Pulse Width Max	2.7 ms
Pulse Width Resolution	83.3 ns
Pulse Code Period Max	25 ms
Measurement Current Min	30 mA
Measurement Current Max	500 mA

Measurement Current Error 10 %

**Board**

Controlled By USB (Mini-USB)

API Object Name RCServo

**Electrical Properties**

Current Consumption Min 30 mA

Current Consumption Max 500 mA

USB Voltage Min 4.8 V DC

USB Voltage Max 5.3 V DC

Continuous Motor Current Max 450 mA

Output Impedance (Motor) 200  $\Omega$

USB Speed Full Speed

**Physical Properties**

Object Temperature Min 0 B°C

Object Temperature Max 70 B°C